Points of General Relativistic Shock Wave Interaction are Regularity Singularities where Spacetime is Not Locally Flat

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Part I

Intuitive Introduction

M. Reintjes GR Shock Interaction are Regularity Singularities

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- In General Relativity (GR), shock waves can be present in the matter content of spacetime.

Intuitive Introduction

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- Einstein tensor, $G^{\mu\nu}$, is determined by metric tensor.
- \longrightarrow How do shock waves effect the metric tensor?

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Central Question:

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Can we transform to different coordinates, such that 2^{nd} order metric derivatives exist point-wise in the new coordinates?

- Across a single shock wave: Yes! (Israel, 1966)
- At points of shock wave interaction: No! (R. and Temple, 2011) \rightarrow "Regularity Singularity"

Part II

Background: Shock Waves in General Relativity

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Some mathematical terminology:

- regularity \equiv handwavy expression refering to degree of differentiability
- f(·) is Lipschitz continuous ≡ f(·) is point-wise differentiable with possibly discontinuous derivatives
- $C^{0,1} \equiv$ set of Lipschitz continuous functions
- C^{1,1} ≡ set of functions whose derivatives are Lipschitz continuous

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A *single* shock wave being present in the Einstein equations is characterized by:

• $\mathcal{T}^{\mu\nu}$ is discontinuous across a hypersurface Σ and continuous elsewhere.

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- $T^{\mu\nu}$ is discontinuous across a hypersurface Σ and continuous elsewhere.
- Across Σ , the Rankine Hugoniot jump conditions hold, that is,

$$[T^{\mu\nu}]N_{\nu}=0,$$

where

- N^{ν} normal to Σ ,
- $[u] := u_L u_R$ denotes the jump in u across Σ
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- $u_{L/R}$ denotes the left/right limit of u to Σ .
- Einstein equations, $G^{\mu\nu} = \kappa T^{\mu\nu}$, hold pointwise away from Σ .

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Remark:

• A very important setting for shock waves in GR are the **Coupled Einstein Euler equations**,

$$\begin{array}{rcl} G^{\mu\nu} &=& \kappa T^{\mu\nu},\\ {\rm div}\,T &=& 0, \end{array}$$

where $T^{\mu\nu} = (\rho + p)u^{\mu}u^{\nu} + pg^{\mu\nu}$, (perfect fluid).

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 Shock waves can form in the relativistic Euler equations, div T = 0, out of smooth initial data.

Part III

The Question of the Metric Regularity

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• In Standard Schwarzschild Coordinates the metric reads

 $ds^{2} = -A(t,r)dt^{2} + B(t,r)dr^{2} + r^{2}\left(d\vartheta^{2} + \sin^{2}(\vartheta)d\varphi^{2}\right),$

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• In such coords the first Einstein equation reads

$$\frac{\partial B}{\partial r} + B\frac{B-1}{r} = \kappa A B^2 r T^{00}.$$

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Conclusion:

- In some coordinates, the Einstein equations contain first order differential equations.
- Thus, if shock waves are present in T^{μν}, the metric is Lipschitz continuous (C^{0,1}), but not continuously differentiable (C¹). Thus, 2nd order derivatives fail to exist point-wise.

Conclusion:

- In some coordinates, the Einstein equations contain first order differential equations.
- Thus, if shock waves are present in T^{μν}, the metric is Lipschitz continuous (C^{0,1}), but not continuously differentiable (C¹). Thus, 2nd order derivatives fail to exist point-wise.

Central Question:

Do there exist coordinates x^{j} such that the metric in the new coordinates, g_{ij} , is $C^{1,1}$ regular?

What's interesting about $C^{0,1}$ versus $C^{1,1}$ metric regularity?

• $C^{1,1}$ -regularity is crucial to define curvature tensors, G_{ij} , R_{ij} ,..., in a point-wise (non-distributional) sense

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- $C^{1,1}$ is a common assumption in GR, e.g., $C^{1,1}$ regularity is required in Singularity Theorems (of Penrose, Hawking and Ellis).
- If one cannot smooth the metric to $C^{1,1}$, it cannot be locally Minkowski!

 $(\Rightarrow$ No observer in free-fall?!)

Part IV

The Metric Regularity Across a Single Shock Surface

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"Israel's Theorem"

(Israel 1966) (see also: Smoller and Temple 1994)

Suppose:

- $g_{\mu\nu}$ is $C^{0,1}$ across a single smooth surface Σ , but smooth away from Σ
- $g_{\mu\nu}$ solves the Einstein equations point-wise away from Σ Then the following is equivalent:
 - There exist a $C^{1,1}$ regular coordinate transformation, such that $g_{\alpha\beta}$ is $C^{1,1}$ regular, w.r.t. partial differentiation in the new coordinates x^{α} .
 - The RH jump conditions, $[T^{\mu\nu}]N_{\nu} = 0$, hold on Σ and $T^{\mu\nu}$ is bounded.

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Lesson:

Across a **single** shock one can always lift metric regularity to $C^{1,1}$!

Part V

The Metric Regularity at Points of Shock Wave Interaction

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However, shock waves can interact.

Can one still lift the metric regularity at points of shock wave collision? (Groah & Temple, 2004)

NO, one cannot! (R. & Temple, 2011)

Before we state our theorem, let me introduce the shock wave interaction we consider:

Points of Regular Shock Wave Interaction in SSC:

Assumption on spacetime:

• Suppose spacetime *M* is **spherically symmetric**.

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Assumption on spacetime:

- Suppose spacetime *M* is **spherically symmetric**.
- Assume Standard Schwarzschild Coordinates (=:SSC) exists around a point *p*, that is, assume the metric reads

$$g = -A(t,r)dt^2 + B(t,r)dr^2 + r^2d\Omega^2,$$

with

$$d\Omega^2 := d\vartheta^2 + \sin^2(\vartheta) d\varphi^2.$$

Assumption on shock waves:

• Assume shock waves are radial, that is, the shock surfaces, Σ_1 and $\Sigma_2,$ are 2-spheres evolving in time.

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- More precisely, Σ_i can be parameterized as

$$\Sigma_i(t,\vartheta,\varphi) = (t,x_i(t),\vartheta,\varphi), \quad x_i(t) > 0, \ (i = 1,2).$$

- Note: $\Sigma_i(t)$ is a 2-sphere with radius $x_i(t)$ and center r = 0.
- Instead of Σ_i it suffices to consider curves γ_i(t) = (t, x_i(t)), (so-called "shock curves").

Definition

- $p \in M$ is a "point of regular shock wave interaction in SSC" if
 - γ_i(t) = (t, x_i(t)), i = 1, 2, are smooth timelike curves defined on t ∈ (-ε, 0), which intersect in p = γ₁(0) = γ₂(0).
 - $T^{\mu\nu}$ is discontinuous across γ_1 and γ_2 .
 - Rankine Hugoniot conditions, $[T^{\mu\nu}]_i(N_i)_{\nu} = 0$, hold across each γ_i , (for i = 1, 2), and in the limit to $t \nearrow 0$.
 - The SSC-metric, $g_{\mu\nu}$, is only $C^{0,1}$ across each shock curve and C^2 off and along them.
 - Einstein equations hold point-wise off Σ_i .
 - Shocks interact with distinct speeds, $\dot{x}_1(0) \neq \dot{x}_2(0)$.

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We expect this structure to be generic for radial shock waves in spherical symmetry, in agreement with the shock collisions simulated in (Vogler, 2011) and existence theory in (Groah & Temple, 2004).

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Let's state our main theorem:

Theorem, (R. and Temple, 2011)

Assume p is "a point of regular shock wave interaction in SSC". Then there does **not** exist a $C^{1,1}$ coordinate transformation, defined in a neighborhood of p, such that both holds:

- The metric components are *C*¹ functions of the new coordinates.
- The metric has a nonzero determinant at p.

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Remark:

We only require two shock waves to be present before (or after) the interaction.

- \implies We address many physical shock wave interaction, e.g.:
 - two shock waves come in; two shock waves go out
 - two shock waves come in; one shock and one rarefaction wave go out
 - two compression waves come in; two shock waves go out

Theorem, (R. and Temple, $2011)^{\circ}$

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Remark on Proof:

The main step is to prove the result for a smaller atlas first,

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Remark on Proof:

The main step is to prove the result for a smaller atlas first, namely, the atlas consisting of "coordinate transformations of the (t, r)-plane", i.e., transformations which keep the SSC angular variables fixed.

Part VI

Proof of Theorem

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Step 1:

 Assume there exist coordinates x^α, such that the transformed metric,

$$g_{\alpha\beta} = J^{\mu}_{\alpha} J^{\nu}_{\beta} g_{\mu\nu}, \qquad (1)$$

is in C^1 , where $J^{\mu}_{\alpha} = \frac{\partial x^{\mu}}{\partial x^{\alpha}}$ (Jacobian) and $g_{\mu\nu}$ metric in SSC.

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u}$ metric in SSC.

• Now, $g_{\alpha\beta}$ being in C^1 implies that, for all $\alpha, \beta, \gamma \in \{0, ..., 3\}$,

$$[g_{\alpha\beta,\gamma}]_i = 0. \tag{2}$$

- $[\cdot]_i$ jump across the shock curve γ_i
- $f_{,\gamma} := \frac{\partial f}{\partial x^{\gamma}}$ denotes differentiation w.r.t. new coords x^{α} .

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- $f_{,\gamma} := \frac{\partial f}{\partial x^{\gamma}}$ denotes differentiation w.r.t. new coords x^{α} .
- Now, substituting (1) into (2) leads to

$$[J^{\mu}_{\alpha,\gamma}]_i J^{\nu}_{\beta} g_{\mu\nu} + [J^{\nu}_{\beta,\gamma}]_i J^{\mu}_{\alpha} g_{\mu\nu} + J^{\mu}_{\alpha} J^{\nu}_{\beta} [g_{\mu\nu,\gamma}]_i = 0.$$

• Observe that above equation,

$$[J^{\mu}_{\alpha,\gamma}]_{i}J^{\nu}_{\beta}g_{\mu\nu} + [J^{\nu}_{\beta,\gamma}]_{i}J^{\mu}_{\alpha}g_{\mu\nu} + J^{\mu}_{\alpha}J^{\nu}_{\beta}[g_{\mu\nu,\gamma}]_{i} = 0, \qquad (3)$$

is necessary condition for smoothing the metric. It is linear in $[J^{\mu}_{\alpha,\gamma}]_{i}.$

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is necessary condition for smoothing the metric. It is linear in $[J^{\mu}_{\alpha,\gamma}]_{i}.$

• A lenghty computation shows that (3) together with the integrability condition,

$$[J^{\mu}_{\alpha,\beta}]_i = [J^{\mu}_{\beta,\alpha}]_i , \qquad (4)$$

has a unique solution $[J^{\mu}_{\alpha,\gamma}]_i$, given in terms of the jumps in the metric derivatives.

• In fact, the unique solution of (3) and (4) is given by:

$$\begin{split} &[J_{0,t}^{t}]_{i} = -\frac{1}{2} \left(\frac{[A_{t}]_{i}}{A} J_{0}^{t} + \frac{[A_{r}]_{i}}{A} J_{0}^{r} \right); \qquad [J_{0,r}^{t}]_{i} = -\frac{1}{2} \left(\frac{[A_{r}]_{i}}{A} J_{0}^{t} + \frac{[B_{t}]_{i}}{A} J_{0}^{r} \right) \\ &[J_{1,t}^{t}]_{i} = -\frac{1}{2} \left(\frac{[A_{t}]_{i}}{A} J_{1}^{t} + \frac{[A_{r}]_{i}}{A} J_{1}^{r} \right); \qquad [J_{1,r}^{t}]_{i} = -\frac{1}{2} \left(\frac{[A_{r}]_{i}}{A} J_{1}^{t} + \frac{[B_{t}]_{i}}{A} J_{1}^{r} \right) \\ &[J_{0,t}^{r}]_{i} = -\frac{1}{2} \left(\frac{[A_{r}]_{i}}{B} J_{0}^{t} + \frac{[B_{t}]_{i}}{B} J_{0}^{r} \right); \qquad [J_{0,r}^{r}]_{i} = -\frac{1}{2} \left(\frac{[B_{t}]_{i}}{B} J_{0}^{t} + \frac{[B_{r}]_{i}}{B} J_{0}^{r} \right) \\ &[J_{1,t}^{r}]_{i} = -\frac{1}{2} \left(\frac{[A_{r}]_{i}}{B} J_{1}^{t} + \frac{[B_{t}]_{i}}{B} J_{1}^{r} \right); \qquad [J_{1,r}^{r}]_{i} = -\frac{1}{2} \left(\frac{[B_{t}]_{i}}{B} J_{1}^{t} + \frac{[B_{r}]_{i}}{B} J_{1}^{r} \right). \end{split}$$

• Notation:

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$$A_t := \frac{\partial A}{\partial t}$$
, ...
• $\mu, \nu \in \{t, r\}$ and $\alpha, \beta \in \{0, 1\}$
• J_0^t denotes the $\mu = t$ and $\alpha = 0$ component of the Jacobian J_{α}^{μ}

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 The above solution [J^μ_{α,γ}]_i is only defined on the shock curves. We now need to introduce functions, J^μ_α, whose derivatives have exactly the discontinuities prescribed by the solution of (3) and (4), that is [J^μ_{α,γ}]_i.

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- Such functions J^{μ}_{α} exist if and only if the Rankine-Hugoniot condition holds across both shocks. The functions J^{μ}_{α} are unique up to addition of C^1 functions.

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- Such functions J^{μ}_{α} exist if and only if the Rankine-Hugoniot condition holds across both shocks. The functions J^{μ}_{α} are unique up to addition of C^1 functions.
- In fact, every function that meets (3) and (4) can be written in the canonical form stated in the following Lemma:

Lemma

If the RH jump condition hold, then there exists a set of functions $J^{\mu}_{\alpha} \in C^{0,1}(\mathcal{N} \cap \overline{\mathbb{R}^2_{-}})$ that satisfies the smoothing condition (5) on $\gamma_i \cap \mathcal{N}$, (i = 1, 2). All such J^{μ}_{α} assume the canonical form

$$\begin{aligned} J_{0}^{t}(t,r) &= \sum_{i} \alpha_{i}(t) |x_{i}(t) - r| + \Phi(t,r) , \quad \alpha_{i}(t) = \frac{[A_{r}]_{i} \phi_{i}(t) + [B_{t}]_{i} \omega_{i}(t)}{4A \circ \gamma_{i}(t)} , \\ J_{1}^{t}(t,r) &= \sum_{i} \beta_{i}(t) |x_{i}(t) - r| + N(t,r) , \quad \beta_{i}(t) = \frac{[A_{r}]_{i} \nu_{i}(t) + [B_{t}]_{i} \zeta_{i}(t)}{4A \circ \gamma_{i}(t)} , \\ J_{0}^{r}(t,r) &= \sum_{i} \delta_{i}(t) |x_{i}(t) - r| + \Omega(t,r) , \quad \delta_{i}(t) = \frac{[B_{t}]_{i} \phi_{i}(t) + [B_{r}]_{i} \omega_{i}(t)}{4B \circ \gamma_{i}(t)} , \\ J_{1}^{r}(t,r) &= \sum_{i} \epsilon_{i}(t) |x_{i}(t) - r| + Z(t,r) , \quad \epsilon_{i}(t) = \frac{[B_{t}]_{i} \nu_{i}(t) + [B_{r}]_{i} \zeta_{i}(t)}{4B \circ \gamma_{i}(t)} , \end{aligned}$$

where

$$\phi_i = \Phi \circ \gamma_i, \quad \omega_i = \Omega \circ \gamma_i, \quad \zeta_i = Z \circ \gamma_i, \quad \nu_i = N \circ \gamma_i, \quad (7)$$

and $\Phi, \Omega, Z, N \in C^{0,1}(\mathcal{N} \cap \overline{\mathbb{R}^2_-})$ have matching derivatives on each shock curve $\gamma_i(t)$,

$$[U_r]_i = 0 = [U_t]_i, (8)$$

for $U = \Phi, \Omega, Z, N, t \in (-\epsilon, 0)$.

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ight)=0.$$

 In above equation, all factors must be non-zero except the last one!
• We conclude that

$$\lim_{t \nearrow 0} Det \ (J^{\mu}_{\alpha} \circ \gamma_{i}(t)) = 0,$$

and thus, since $g_{\alpha\beta} = J^{\mu}_{\alpha} J^{\nu}_{\beta} g_{\mu\nu}$, we proved
$$\lim_{t \nearrow 0} Det \ (g_{\alpha\beta} \circ \gamma_{i}(t)) = 0.$$

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• We conclude that

$$\begin{split} &\lim_{t \nearrow 0} Det \; (J^{\mu}_{\alpha} \circ \gamma_i(t)) = 0, \\ \text{and thus, since } g_{\alpha\beta} = J^{\mu}_{\alpha} J^{\nu}_{\beta} g_{\mu\nu}, \text{ we proved} \\ &\lim_{t \nearrow 0} Det \; (g_{\alpha\beta} \circ \gamma_i(t)) = 0. \end{split}$$

• This completes the proof.

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Part VII

Summary and Consequences

M. Reintjes GR Shock Interaction are Regularity Singularities

• At points, *p*, of regular shock interaction in SSC the gravitational metric suffers a **non-removable** lack of *C*¹ regularity.

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- At points, *p*, of regular shock interaction in SSC the gravitational metric suffers a **non-removable** lack of *C*¹ regularity.
- In particular, there exist (non-removable) distributional second order metric derivatives, but due to cancelation the spacetime curvature remains bounded.
- At *p*, spacetime is **not locally inertial**, that is, there do not exist coordinates *x^j*, such that the metric satisfies:

•
$$g_{ij}(p) = \eta_{ij}$$
, where $\eta_{ij} = diag(-1, 1, 1, 1)$,

•
$$g_{ij,l}(p)=0$$

• $g_{ij,kl}$ are bounded on some neighborhood of p.

Part VIII

What's the physics behind all this?

M. Reintjes GR Shock Interaction are Regularity Singularities

 As spacetime fails to be locally inertial at points of shock wave collision and second order metric derivatives being distributional at such points, regularity singularities might be observable astrophysical objects.

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Thank you for your attention!

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